

### 7.3 The Definite Integral as the Limit of Riemann Sums

#### Introduction

This section presents the actual *definition* of the definite integral. As previously noted, one is often able to bypass this definition, due to the Fundamental Theorem of Integral Calculus. However, *it is still extremely important that you see this definition*, for three reasons:

- The definition provides the motivation for the notation

$$\int_a^b f(x) dx$$

that is used in connection with the definite integral.

- The definition provides the *intuition* that mathematicians use to help them develop many useful formulas involving the definite integral; e.g., finding the area between two curves and finding volumes of revolution. These formulas are presented later on in this chapter.
- The definition provides the justification for numerical methods used to approximate  $\int_a^b f(x) dx$ , when one is unable to obtain an antiderivative of  $f$ .

#### EXERCISE 1

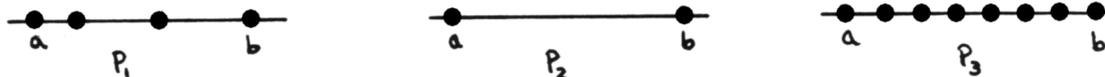
♣ What are the three reasons for which it is important that you see the *definition* of the definite integral?

*partition of an interval*  $[a, b]$

We begin with some definitions.

A *partition* of the interval  $[a, b]$  is a finite collection (set) of points from  $[a, b]$  that includes the endpoints  $a$  and  $b$ .

Some partitions of  $[a, b]$  are shown below:



By convention, when one writes a partition

$$P = \{x_0, x_1, x_2, \dots, x_{n-1}, x_n\}$$

of  $[a, b]$ , it is assumed that:

- $x_0 = a$ ; that is, the first point in the partition is the left-hand endpoint  $a$
- $x_n = b$ ; that is, the last point in the partition is the right-hand endpoint  $b$
- The points are listed in *increasing* order, so that:

$$x_0 < x_1 < x_2 < \dots < x_{n-1} < x_n$$

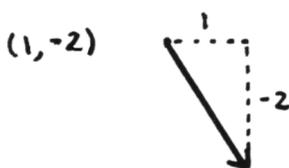
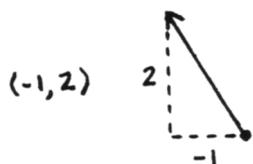
Observe that a partition of  $[a, b]$  naturally breaks the interval  $[a, b]$  into *non-overlapping subintervals* whose union is the entire interval  $[a, b]$ :

$$\left[ \overbrace{x_0}^{=a}, x_1 \right) \cup [x_1, x_2) \cup \dots \cup [x_{n-2}, x_{n-1}) \cup [x_{n-1}, \overbrace{x_n}^{=b}]$$

**EXERCISE 2**

- ♣ 1. How many points are in the partition  $P = \{1, 2, 2.5, 3\}$  of  $[1, 3]$ ? Show these points on a number line. Into how many subintervals is  $[1, 3]$  divided by this partition?
- ♣ 2. How many points are in the partition  $P = \{x_0, x_1, \dots, x_n\}$  of an interval  $[a, b]$ ? Into how many subintervals is  $[a, b]$  divided by this partition?

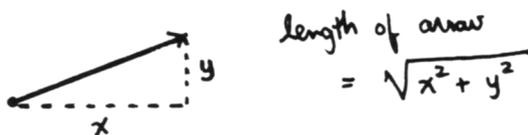
*norm*



A *norm* is a tool used in mathematics to measure the *size* of objects.

For example, the absolute value  $|\cdot|$  measures the size of real numbers; the function that maps a real number  $x$  to its ‘size’  $|x|$  is a *norm* on  $\mathbb{R}$ .

As a second example, a natural way to ‘measure the size’ of a pair of real numbers  $(x, y)$  is to first look at the arrow (vector) representing  $(x, y)$ , and then measure its length;



the function that maps a pair  $(x, y)$  of real numbers to its ‘size’  $\sqrt{x^2 + y^2}$  is a *norm* on the set of all ordered pairs.

*measuring the ‘size’ of a partition*

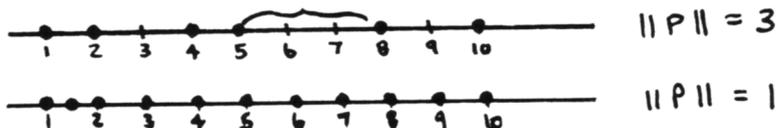
We need a way of measuring the *size* of a partition of  $[a, b]$ . We want to say that the partition is ‘small’ if the lengths of *all* the subintervals are small. Observe that if the length of the *longest* subinterval is small, then the lengths of *all* the subintervals must be small. This motivates the next definition.

*norm of a partition;*  
 $\|P\|$

Define  $\|P\|$  (read as the ‘*norm of the partition P*’) to be the length of the *longest* subinterval in the partition  $P$ .

For example, if  $P$  is the partition  $\{1, 2, 4, 5, 8, 10\}$  of  $[1, 10]$ , then  $\|P\| = 3$ , since the length of the longest subinterval is 3.

Also, if  $P = \{1, 1.5, 2, 3, 4, 5, 6, 7, 8, 9, 10\}$ , then  $\|P\| = 1$ , since the length of the longest subinterval is 1.



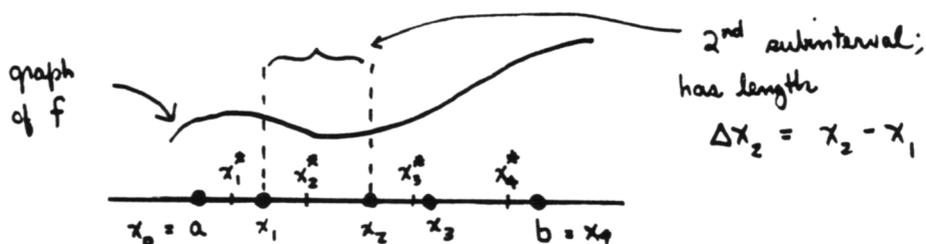
The closer  $\|P\|$  is to zero, the smaller the subintervals, and hence the more points there are in  $P$ .

**EXERCISE 3**

- ♣ 1. Give a partition of  $[0, 1]$  that has norm  $\frac{1}{2}$ . How many points are in this partition?
- ♣ 2. Give a different partition of  $[0, 1]$  that has norm  $\frac{1}{2}$ . How many points are in this partition?
- ♣ 3. What are the *fewest* number of points that you must have in a partition of  $[0, 1]$ , in order for it to have norm  $\frac{1}{2}$ ?

Riemann Sum for  $f$ ;  
 $x_i^*$  is our  
 choice from the  
 $i^{\text{th}}$  subinterval,  
 which has length  
 $\Delta x_i$

Let  $f$  be continuous on  $[a, b]$ , and let  $P = \{x_0, \dots, x_n\}$  be any partition of the interval  $[a, b]$ , as illustrated below.



In each of the  $n$  subintervals, choose any point; let  $x_i^*$  denote the choice from the  $i^{\text{th}}$  subinterval.

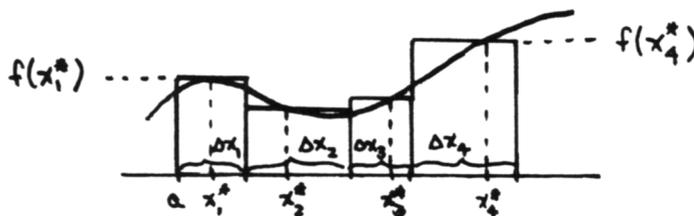
Also, let  $\Delta x_i := x_i - x_{i-1}$  denote the length of the  $i^{\text{th}}$  subinterval.

Then, the sum

$$R(P) := f(x_1^*)\Delta x_1 + f(x_2^*)\Delta x_2 + \dots + f(x_n^*)\Delta x_n$$

is called a Riemann sum for  $f$ , corresponding to the partition  $P$ . ('Riemann' is pronounced REE-mon.)

Observe that if  $f$  is nonnegative, then the sum  $R(P)$  represents the sum of the areas of the rectangles shown below, which approximates the area under the graph of  $f$  on  $[a, b]$ .



**EXERCISE 4**

Consider the partition  $P = \{0, 1, 2, 3, 4\}$  of  $[0, 4]$ . Let  $f(x) = x^2$ .

- ♣ 1. Choose the midpoint from each subinterval of  $P$ . That is, choose:

$$x_1^* = 0.5, \quad x_2^* = 1.5, \quad x_3^* = 2.5, \quad x_4^* = 3.5$$

Make a sketch that shows the graph of  $f$ , the partition  $P$ , and the choices  $x_i^*$ .

- ♣ 2. On each subinterval, draw a rectangle with height  $f(x_i^*)$ .
- ♣ 3. Sum the areas of these rectangles. That is, find the Riemann sum for  $f$  corresponding to the choices  $x_i^*$ .
- ♣ 4. What is the actual area under the graph under  $f$  on  $[0, 4]$ ?

**EXERCISE 5**

♣ Repeat the previous exercise, except this time with the partition

$$\{0, 0.5, 1, 1.5, 2, 2.5, 3, 3.5, 4\}$$

of  $[0, 4]$ . Again choose the  $x_i^*$  to be the midpoints of each subinterval.

This time, what is the Riemann sum for  $f$  corresponding to the partition  $P$  and choices  $x_i^*$ ?

obtain the  
definite integral  
by letting  $\|P\| \rightarrow 0$

Under the hypothesis that  $f$  is continuous on  $[a, b]$ , it can be proven that as one chooses partitions with smaller and smaller norms, the corresponding Riemann sums approach a unique number.

We define this unique number to be the *definite integral of  $f$  on  $[a, b]$* , denoted by  $\int_a^b f(x) dx$ .

more precisely

More precisely, as  $\|P\| \rightarrow 0$ ,  $R(P) \rightarrow \int_a^b f(x) dx$ .

That is, we can get the numbers  $R(P)$  as close to  $\int_a^b f(x) dx$  as desired, merely by choosing a partition  $P$  of  $[a, b]$  with norm sufficiently close to 0.

In other words, for every  $\epsilon > 0$ , there exists  $\delta > 0$ , such that if a partition  $P$  is chosen with  $\|P\| < \delta$ , then:

$$\left| R(P) - \int_a^b f(x) dx \right| < \epsilon$$

Rephrasing yet one more time, we can get the Riemann sum  $R(P)$  as close to the number  $\int_a^b f(x) dx$  as desired, by choosing a partition  $P$  of  $[a, b]$  that has sufficiently small subintervals.

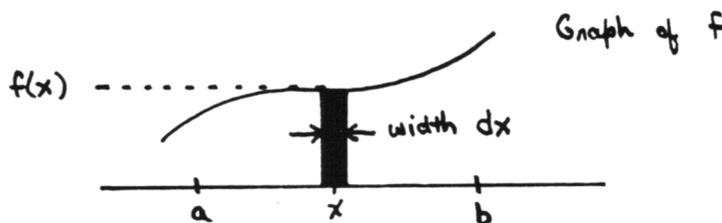
It is clear from the definition of  $\int_a^b f(x) dx$  that this integral gives information about the *area* trapped between the graph of  $f$  and the  $x$ -axis.

If  $f$  is positive on  $[a, b]$ , then any Riemann sum  $R(P)$  is also positive, and approximates the area under the graph of  $f$  on  $[a, b]$ .

If  $f$  is negative on  $[a, b]$ , then any Riemann sum  $R(P)$  is also negative. (♣ Why?) The magnitude of the negative number  $R(P)$  approximates the area trapped between the graph of  $f$  and the  $x$ -axis on  $[a, b]$ .

motivation for  
the notation  $\int_a^b f(x) dx$ ;  
 $f(x) dx$  is  
the (signed) area of  
a rectangle, with  
width  $dx$ , and  
height  $f(x)$

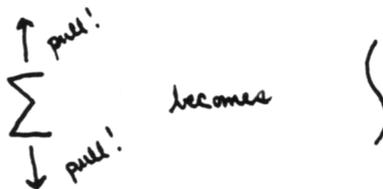
The definition of the definite integral of  $f$  on  $[a, b]$  provides the motivation for the notation  $\int_a^b f(x) dx$  used, as follows:



Think of  $dx$  as an *infinitesimally small piece of the  $x$ -axis*. At a point  $x$  between  $a$  and  $b$ , construct a rectangle of width  $dx$  and height  $f(x)$ . Then (using calculus!) ‘sum’ these rectangles as  $x$  varies from  $a$  to  $b$ .

$\sum$   
becomes  
 $\int$

The integral sign  $\int$  is, therefore, a kind of *super sum*; indeed, one can think of obtaining it from the summation sign  $\sum$  used for finite sums by stretching it out!



*integration is an (infinite) summation process*

That is, *integration is really an (infinite) summation process.*

If seeing the notation  $\int_a^b f(x) dx$  conjures an image of a limit of Riemann sums, then it is a successful notation.

### QUICK QUIZ

*sample questions*

1. What is a *partition* of an interval  $[a, b]$ ?
2. Give two different partitions of  $[1, 3]$  that have norm  $1/2$ .
3. Let  $f(x) = x^2$ , and take the partition  $\{0, 1, 2, 3\}$  of the interval  $[0, 3]$ . Is there a unique Riemann sum for  $f$  corresponding to this partition? Comment.
4. What picture might you think of when you see the notation  $\int_a^b f(x) dx$ ?

### KEYWORDS

*for this section*

*Three reasons for seeing the definition of the definite integral, partition of an interval, norm, norm of a partition, Riemann sum for  $f$ , obtain the definite integral by letting  $\|P\| \rightarrow 0$ , motivation for the notation  $\int_a^b f(x) dx$ , integration is an (infinite) summation process.*

### END-OF-SECTION EXERCISES

- ♣ Classify each entry below as an expression (EXP) or a sentence (SEN).
  - ♣ For any *sentence*, state whether it is TRUE (T), FALSE (F), or CONDITIONAL (C).
1.  $\int x^2 dx$
  2.  $\int_0^1 x^2 dx$
  3.  $\int_0^1 x^2 dx = \frac{1}{3}$
  4. The integral  $\int_a^b f(x) dx$  gives the magnitude of the area bounded between the graph of  $f$  and the  $x$ -axis on  $[a, b]$ .
  5. If  $a < b$ , then the integral  $\int_a^b e^x$  gives the magnitude of the area bounded between the graph of  $y = e^x$  and the  $x$ -axis on  $[a, b]$ .
  6. If  $P$  is a partition of  $[a, b]$ , then a Riemann sum  $R(P)$  corresponding to  $f$  is an approximation to  $\int_a^b f(x) dx$ .
  7. If  $g$  is twice differentiable on the interval  $[a, b]$ , then  $\int_a^b g'(x) dx = g(b) - g(a)$ .
  8. If  $a < b$  and  $f$  is continuous on  $[a, b]$ , then  $\int_a^b |f(x)| dx \geq 0$ .
  9. If  $a < b$  and  $f$  is continuous on  $[a, b]$ , then  $\int_a^b (-|f(x)|) dx \leq 0$ .
  10. For all real numbers  $a$  and  $b$ ,  $\int_a^b x^2 dx = \int_a^b t^2 dt$ .